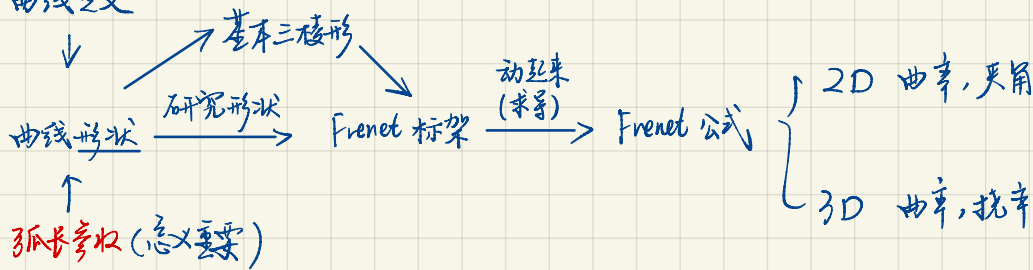


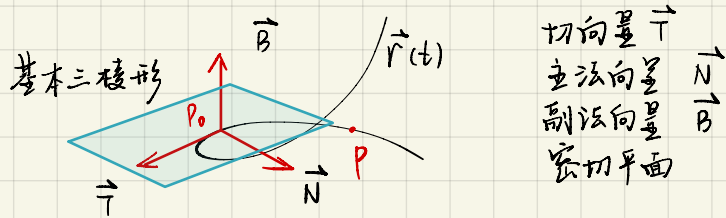
## Chap 2. 曲线论.

要点: 曲线定义



参考笔记 (可在 personal page 查看) .

详细内容 (证明过程见 notes (in personal page))



切向量  $\vec{T}$   
 主法向量  $\vec{N}$   
 副法向量  $\vec{B}$   
 密切平面

$$\vec{T} = \vec{r}'(t_0) = (x'(t_0), y'(t_0), z'(t_0)), \quad \vec{r}(t_0) = (x_0, y_0, z_0)$$

切线  $\frac{x-x_0}{x'(t_0)} = \frac{y-y_0}{y'(t_0)} = \frac{z-z_0}{z'(t_0)}$

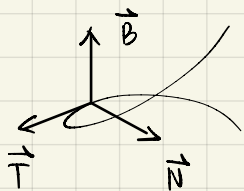
密切平面方程  $\vec{P_0P} \cdot (\vec{r}'(t_0) \times \vec{r}''(t_0)) = 0$ ,  $P$  为任一点  $(x, y, z)$

法平面方程  $\vec{P_0P} \cdot \vec{r}'(t_0) = 0$

密切平面法向量:  $\vec{r}'(t_0) \times \vec{r}''(t_0)$

$\Rightarrow$  从切平面法向量  $\vec{r}' \times (\vec{r}' \times \vec{r}'')$  外积造正交

由基本三棱形可得 Frenet 标架, 只要多一步单位化



$$\vec{T} = \vec{r}'(t)$$

$$\vec{B} = \frac{\vec{r}'(t) \times \vec{r}''(t)}{|\vec{r}'(t) \times \vec{r}''(t)|} \quad (\text{密切平面的法向量})$$

$$\vec{N} = \vec{B} \times \vec{T} \quad \text{注意顺序!}$$

弧长参数  $s(t) = \int_a^t |\vec{r}'(z)| dz \Rightarrow s'(t) = |\vec{r}'(t)| > 0$  (正则曲线, 其实就是光滑)

$\Rightarrow s(t) \nearrow \Rightarrow$  有反函数.

弧长参数下的 Frenet frame.  $\vec{r}(s)$  写成  $\dot{r}(s)$ , 为了好看.

$$\vec{T} = \dot{r}(s), \quad \vec{N} = \frac{\ddot{r}(s)}{|\ddot{r}(s)|}, \quad \vec{B} = \vec{T} \times \vec{N}$$

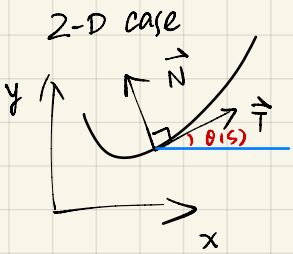
( $\dot{r}(s)$  已是单位向量)

让 Frenet frame 动起来

↓ 推导

★ Frenet 公式 (3-dimensional) 设  $\vec{r} = \vec{r}(s)$ ,  $s$  弧长参数

$$\begin{cases} \dot{\vec{T}} = \kappa \vec{N} \Rightarrow \ddot{\vec{r}}(s) = \kappa \vec{N} \Rightarrow \kappa = |\ddot{\vec{r}}(s)| \\ \dot{\vec{N}} = -\kappa \vec{T} + \tau \vec{B} \\ \dot{\vec{B}} = -\tau \vec{N} \end{cases}$$



$\vec{r} = \vec{r}(s) = (x(s), y(s))$ ,  $s$  弧长参数

$$\dot{\vec{r}}(s) = (\dot{x}(s), \dot{y}(s))$$

$$\| \dot{\vec{r}}(s) \|^2 = \dot{x}(s)^2 + \dot{y}(s)^2 = 1$$

$$\text{写成 } \dot{\vec{r}}(s) = (\cos \theta(s), \sin \theta(s)) =: \vec{T}$$

$$\vec{T} \text{ 逆时针转 } \frac{\pi}{2} \text{ 得到 } \vec{N} = (\cos(\theta + \frac{\pi}{2}), \sin(\theta + \frac{\pi}{2})) = (-\sin \theta(s), \cos \theta(s)) = (-\dot{y}, \dot{x})$$

not guilty

$$\dot{\vec{T}} = \kappa_r \vec{N}, \quad \dot{\vec{N}} = -\kappa_r \vec{T}$$

$$\dot{\vec{T}} = \frac{d\vec{T}}{ds} = \left( -\sin \theta \frac{d\theta}{ds}, \cos \theta \frac{d\theta}{ds} \right) = \frac{d\theta}{ds} (-\sin \theta, \cos \theta) = \frac{d\theta}{ds} \vec{N}$$

$$\Rightarrow \kappa_r = \frac{d\theta}{ds} \Rightarrow \theta = \int_0^s \kappa_r(u) du \Rightarrow \theta(s)$$

$$(\ddot{x}, \ddot{y}) = \kappa_r (-\dot{y}, \dot{x})$$

$$\begin{aligned} \parallel \dot{x} &= \cos \theta \\ \parallel \dot{y} &= \sin \theta \\ \text{积分} &\begin{cases} x = x(s) \\ y = y(s) \end{cases} \end{aligned}$$

$$\begin{cases} \ddot{x} = -\kappa_r \dot{y} \\ \ddot{y} = \kappa_r \dot{x} \end{cases}$$

$$\parallel \dot{x}^2 + \dot{y}^2 = 1$$

$$\ddot{y}\dot{x} - \dot{y}\ddot{x} = \kappa_r$$

## 双曲函数

$$\sinh x = \frac{e^x - e^{-x}}{2} = \frac{e^{2x} - 1}{2e^x} = \frac{1 - e^{-2x}}{2e^{-x}}$$

• Hyperbolic cosine: the even part of the exponential function, that is,

$$\cosh x = \frac{e^x + e^{-x}}{2} = \frac{e^{2x} + 1}{2e^x} = \frac{1 + e^{-2x}}{2e^{-x}}$$

Sums of arguments (cos)

$$\begin{aligned} \sinh(x+y) &= \sinh x \cosh y + \cosh x \sinh y \\ \cosh(x+y) &= \cosh x \cosh y + \sinh x \sinh y \\ \tanh(x+y) &= \frac{\tanh x + \tanh y}{1 + \tanh x \tanh y} \end{aligned}$$

particularly

$$\begin{aligned} \cosh(2x) &= \sinh^2 x + \cosh^2 x = 2\sinh^2 x + 1 = 2\cosh^2 x - 1 \\ \sinh(2x) &= 2\sinh x \cosh x \\ \tanh(2x) &= \frac{2\tanh x}{1 + \tanh^2 x} \end{aligned}$$

Also:

$$\begin{aligned} \sinh x + \sinh y &= 2\sinh\left(\frac{x+y}{2}\right) \cosh\left(\frac{x-y}{2}\right) \\ \cosh x + \cosh y &= 2\cosh\left(\frac{x+y}{2}\right) \cosh\left(\frac{x-y}{2}\right) \end{aligned}$$

$$\frac{d}{dx} \sinh x = \cosh x$$

$$\frac{d}{dx} \cosh x = \sinh x$$

没有负号!

$$\begin{aligned} \sinh^2 t - \cosh^2 t &= \frac{1}{4} [(e^x - e^{-x})^2 - (e^x + e^{-x})^2] = -1 \\ \cosh^2 t - \sinh^2 t &= 1 \end{aligned}$$

5. 证:  $E^3$  正则曲线  $\vec{r}(t)$  的曲率为  $k(t) = \frac{|\vec{r}'(t) \times \vec{r}''(t)|}{|\vec{r}'(t)|^3}$ ,  $\tau(t) = \frac{(\vec{r}', \vec{r}'', \vec{r}''')}{|\vec{r}' \times \vec{r}''|^2}$

一般参数的曲率. Frenet 公式(做. (结论要背))

pf. key: Chain Rule

弧长  $s(t) = \int_0^t |\vec{r}'(u)| du$

$$\begin{cases} \dot{T} = k\vec{N} \\ \dot{N} = -k\vec{T} + \tau\vec{B} \\ \dot{B} = -\tau\vec{N} \end{cases}$$

$$\Rightarrow \frac{ds}{dt} = |\vec{r}'(t)| \Rightarrow \frac{dt}{ds} = \frac{1}{|\vec{r}'(t)|}$$

$$\vec{T}(s) = \frac{d\vec{r}}{ds} = \frac{d\vec{r}}{dt} \frac{dt}{ds} = \vec{r}' \frac{dt}{ds},$$

$$\begin{aligned} \dot{T}(s) &= \frac{d}{ds} \left( \vec{r}' \frac{dt}{ds} \right) = \frac{d\vec{r}'}{ds} \frac{dt}{ds} + \vec{r}' \frac{d^2t}{ds^2} \\ &= \frac{d\vec{r}'}{dt} \frac{dt}{ds} \frac{dt}{ds} + \vec{r}' \frac{d^2t}{ds^2} \\ &= \vec{r}'' \left( \frac{dt}{ds} \right)^2 + \vec{r}' \frac{d^2t}{ds^2} \end{aligned}$$

$$\dot{T} \times \vec{T} = k\vec{N} \times \vec{T} = -k\vec{B}$$

$$|\dot{T} \times \vec{T}| = k, \text{ 现在算}$$

$$\begin{aligned} \dot{T} \times \vec{T} &= \left( \vec{r}'' \left( \frac{dt}{ds} \right)^2 + \vec{r}' \frac{d^2t}{ds^2} \right) \times \left( \vec{r}' \frac{dt}{ds} \right) \\ &= \vec{r}'' \times \vec{r}' \left( \frac{dt}{ds} \right)^3 \\ &= \frac{\vec{r}'(t) \times \vec{r}''(t)}{|\vec{r}'(t)|^3} \end{aligned}$$

#### 4. 求曲率又挠率 用ex5的公式

$$(1) \vec{r}(t) = (a \cosh t, a \sinh t, bt)$$

$$\text{Sol. } \vec{r}'(t) = (a \sinh t, a \cosh t, b), \quad \vec{r}''(t) = (a \cosh t, a \sinh t, 0)$$

$$\vec{r}'(t) \times \vec{r}''(t) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a \sinh t & a \cosh t & b \\ a \cosh t & a \sinh t & 0 \end{vmatrix} = (-ab \sinh t, ab \cosh t, \underbrace{a^2(\sinh^2 t - \cosh^2 t)}_{= -a^2})$$

$$|\vec{r}'(t) \times \vec{r}''(t)| = (a^2 b^2 \sinh^2 t + a^2 b^2 \cosh^2 t + a^4)^{\frac{1}{2}}$$

$$= a(b^2 \sinh^2 t + b^2 \cosh^2 t + a^2)^{\frac{1}{2}}$$

$$|\vec{r}'(t)| = a(\sinh^2 t + \cosh^2 t)^{\frac{1}{2}}$$

$$|\vec{r}'(t)|^3 = a^3(\sinh^2 t + \cosh^2 t)^{\frac{3}{2}}$$

$$(2) \vec{r}(t) = (3t - t^2, 3t^2, 3t + t^2)$$

$$\vec{r}'(t) = (3 - 2t, 6t, 3 + 2t)$$

$$\vec{r}''(t) = (-2, 6, 2)$$

$$\vec{r}'''(t) = (0, 0, 0)$$

$$\vec{r}'(t) \times \vec{r}''(t) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 3-2t & 6t & 3+2t \\ -2 & 6 & 2 \end{vmatrix} = (-18, -12, 18)$$

$$|\vec{r}'(t) \times \vec{r}''(t)| = 6\sqrt{22}$$

$$|\vec{r}'(t)|^2 = (3-2t)^2 + 36t^2 + (3+2t)^2$$

$$= 18 + 8t^2 + 36t^2$$

$$= 44t^2 + 18 \Rightarrow |\vec{r}'(t)| = (44t^2 + 18)^{\frac{1}{2}}$$

$$\kappa(t) = \frac{|\vec{r}'(t) \times \vec{r}''(t)|}{|\vec{r}'(t)|^3} = \frac{6\sqrt{22}}{(44t^2 + 18)^{\frac{3}{2}}}$$

$\tau = 0$ . Since 有一行全为0.

13. (1) 求曲线  $k(s) = \frac{a}{a^2+s^2}$  ( $s$  是弧长参数) 的平面曲线

$$\begin{aligned} \text{sol. } \frac{d\theta}{ds} &= \frac{a}{a^2+s^2}, \quad \theta = \int_0^s \frac{a}{a^2+u^2} du \\ &= a \int_0^s \frac{1}{a^2(1+(\frac{u}{a})^2)} du \\ &= \int_0^s \frac{1}{1+(\frac{u}{a})^2} d(\frac{u}{a}) \\ &= \arctan \frac{s}{a} \end{aligned}$$

$$\vec{r}(s) = (\cos\theta(s), \sin\theta(s)) = \left( \cos\left(\arctan\frac{s}{a}\right), \sin\left(\arctan\frac{s}{a}\right) \right)$$

继续换元: 令  $\theta = \arctan \frac{s}{a}$ ,  $\tan\theta = \frac{s}{a}$ ,  $s = a \tan\theta$ ,  $ds = a \sec^2\theta d\theta$

$$\int \cos\left(\arctan\frac{s}{a}\right) ds = \int a \cos\theta \sec^2\theta d\theta = a \int \sec\theta d\theta = a \int \frac{1}{\cos\theta} d\theta$$

recall  $\int \sec\theta d\theta$

$$= a \log(\sec\theta + \tan\theta)$$

$$d(\sec\theta + \tan\theta) = (\tan\theta \sec\theta + \sec^2\theta) d\theta = \sec\theta(\sec\theta + \tan\theta) d\theta$$

$$\int \sec\theta \frac{\sec\theta + \tan\theta}{\sec\theta + \tan\theta} d\theta = \int \frac{1}{\sec\theta + \tan\theta} d(\sec\theta + \tan\theta) = \log(\sec\theta + \tan\theta)$$

$$\tan\theta = \frac{s}{a} \quad \begin{array}{c} \sqrt{a^2+s^2} \\ \backslash \\ a \end{array} \quad s \quad \sec\theta = \frac{\sqrt{a^2+s^2}}{a}$$

$$\int \cos\left(\arctan\frac{s}{a}\right) ds = a \log\left(\frac{s + \sqrt{a^2+s^2}}{a}\right)$$

$$\begin{aligned} \int \sin\left(\arctan\frac{s}{a}\right) ds &= \int a \sin\theta \sec^2\theta d\theta = a \int \frac{\sin\theta}{\cos^2\theta} d\theta = a \int \tan\theta \sec\theta d\theta \\ &= a \sec\theta = \sqrt{a^2+s^2} \end{aligned}$$

$$\Rightarrow \vec{r}(s) = \left( a \log\left(\frac{s + \sqrt{a^2+s^2}}{a}\right), \sqrt{a^2+s^2} \right)$$

(2)  $k(s) = \frac{1}{\sqrt{a^2-s^2}}$  ( $s$  弧长参数)

$$\text{解: } \theta(s) = \int_0^s \frac{1}{\sqrt{a^2-u^2}} ds = \arcsin \frac{s}{a}$$

$$\Rightarrow \sin\theta = \frac{s}{a}, \quad s = a \sin\theta, \quad ds = a \cos\theta d\theta$$

$$\int \sin\theta(s) ds = \int \frac{s}{a} a \cos\theta d\theta = s \sin\theta = s \cdot \frac{s}{a} = \frac{s^2}{a}$$

6. (Not HW) 证:  $\vec{r}(s) = \left( \frac{(1+s)^{\frac{3}{2}}}{3}, \frac{(1-s)^{\frac{3}{2}}}{3}, \frac{s}{\sqrt{2}} \right)$  ( $-1 < s < 1$ )

以  $s$  为弧长参数, 并求它的曲率, 挠率和 Frenet 标架

pf.  $\frac{d\vec{r}}{ds} = \left( \frac{3}{2} \cdot \frac{(1+s)^{\frac{1}{2}}}{3}, -\frac{3}{2} \cdot \frac{(1-s)^{\frac{1}{2}}}{3}, \frac{1}{\sqrt{2}} \right)$

$\left| \frac{d\vec{r}}{ds} \right|^2 = \frac{1}{4}(1+s) + \frac{1}{4}(1-s) + \frac{1}{2} = 1 \Rightarrow \vec{r}(s)$  的参数  $s$  为弧长参数.

$\dot{\vec{r}}(s) = \left( \frac{1}{2}(1+s)^{\frac{1}{2}}, -\frac{1}{2}(1-s)^{\frac{1}{2}}, \frac{1}{\sqrt{2}} \right) = \vec{T}$

$\ddot{\vec{r}}(s) = \left( \frac{1}{4}(1+s)^{-\frac{1}{2}}, \frac{1}{4}(1-s)^{-\frac{1}{2}}, 0 \right)$

$|\ddot{\vec{r}}(s)| = \left( \frac{1}{16}(1+s)^{-1} + \frac{1}{16}(1-s)^{-1} \right)^{\frac{1}{2}} = \frac{1}{4} \left( (1+s)^{-1} + (1-s)^{-1} \right)^{\frac{1}{2}} = \frac{\sqrt{2}}{4} (1-s^2)^{-\frac{1}{2}}$

$\vec{N} = \frac{\ddot{\vec{r}}(s)}{|\ddot{\vec{r}}(s)|} = \frac{\left( (1+s)^{-\frac{1}{2}}, (1-s)^{-\frac{1}{2}}, 0 \right)}{\left( (1+s)^{-1} + (1-s)^{-1} \right)^{\frac{1}{2}}} = \frac{1}{\sqrt{2}} (1+s)^{\frac{1}{2}} (1-s)^{\frac{1}{2}} \left( (1+s)^{-\frac{1}{2}}, (1-s)^{-\frac{1}{2}}, 0 \right)$   
 $= \frac{1}{\sqrt{2}} \left( (1-s)^{\frac{1}{2}}, (1+s)^{\frac{1}{2}}, 0 \right), \quad \dot{\vec{N}} = \frac{1}{2\sqrt{2}} \left( -(1-s)^{-\frac{1}{2}}, (1+s)^{-\frac{1}{2}}, 0 \right)$

$\vec{B} = \vec{T} \times \vec{N} = \frac{1}{\sqrt{2}} \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ (1-s)^{\frac{1}{2}} & (1+s)^{\frac{1}{2}} & 0 \\ \frac{1}{2}(1+s)^{\frac{1}{2}} & -\frac{1}{2}(1-s)^{\frac{1}{2}} & \frac{1}{\sqrt{2}} \end{vmatrix} = -\left( \frac{1}{2}(1+s)^{\frac{1}{2}}, \frac{1}{2}(1-s)^{\frac{1}{2}}, -\frac{1}{\sqrt{2}} \right) \left( -\frac{1}{2}(1+s)^{\frac{1}{2}}, \frac{1}{2}(1-s)^{\frac{1}{2}}, \frac{1}{\sqrt{2}} \right)$   
 $\dot{\vec{B}} = \left( -\frac{1}{4}(1+s)^{-\frac{1}{2}}, \frac{1}{4}(1-s)^{-\frac{1}{2}}, \frac{1}{\sqrt{2}} \right)$

Frenet 公式:  $\begin{cases} \dot{\vec{T}} = \kappa \vec{N} \\ \dot{\vec{N}} = -\kappa \vec{T} + \tau \vec{B} \\ \dot{\vec{B}} = -\tau \vec{N} \end{cases}$

$\dot{\vec{B}} \cdot \vec{N} = \frac{1}{4\sqrt{2}} \left( \frac{-\sqrt{1-s}}{\sqrt{1+s}} - \frac{\sqrt{1+s}}{\sqrt{1-s}} \right)$   
 $= -\frac{1}{4\sqrt{2}} \frac{1-s+1+s}{\sqrt{1-s^2}} = -\frac{1}{2\sqrt{2}} (1-s^2)^{-\frac{1}{2}}$

$\Rightarrow$  作内积  $\dot{\vec{B}} \cdot \vec{N} = -\tau$   
 $\therefore \tau = \frac{1}{2\sqrt{2}} \frac{0}{\sqrt{1-s^2}}$

$\tau = \frac{1}{2\sqrt{2}} (1-s^2)^{-\frac{1}{2}}$

